

**APM2616**

October/November 2010

**COMPUTER ALGEBRA**

Duration 2 Hours

100 Marks

EXAMINERS .

FIRST

SECOND

DR JMW MUNGANGA

DR R MARITZ

This examination paper remains the property of the University of South Africa and may not be removed from the examination room.

This paper consists of 3 pages

Answer all the questions

**QUESTION 1**We define the function  $f : \mathbb{N} \rightarrow \mathbb{N}$  by

$$f(x) = \begin{cases} 3x + 1 & \text{for } x \text{ odd,} \\ \frac{x}{2} & \text{for } x \text{ even} \end{cases}$$

Write a program which on input  $x_0$  returns the smallest index  $i$  with  $x_i = 1$ 

[20]

**QUESTION 2**

Compute the general solution of the system of linear equations

$$\begin{cases} a + b + c + d + e = 1 \\ a + 2b + 3c + 4d + 5e = 2 \\ a - 2b - 3c - 4d - 5e = 2 \\ a - b - c - d - e = 3 \end{cases}$$

How many free parameters does the solution have?

[20]

**QUESTION 3**Determine the solution  $y(x)$  for each of the following initial value problems

(a)

$$y' - y \sin x = 0, \quad y'(1) = 1$$

(10)

[TURN OVER]

(b)

$$2y' + \frac{y}{x} = 0, \quad y'(1) = \pi.$$

(10)

[20]

**QUESTION 4**

Let  $rd$  denote the rounding function mapping a real point  $x$  to the nearest integer. Plot the function

$$f(x) = \frac{|x - rd(x)|}{x}$$

on the interval  $[1, 30]$

[20]

**QUESTION 5**

Write a complete  $\text{\LaTeX}$  script that reproduces the document printed on page 3

**Please take note that manual references and manual labelling of equations, pages and citations will not be allowed.**

**[TURN OVER]**

# Suspension of Flexible Fibres In a Newtonian Fluid

JM MUNGANGA

May 26, 2010

## 1 The dissipation Inequality

### 1.1 Free Energy

If the free energy is denoted by  $\Psi$ , then the local form of the second law is the dissipation inequality[1]

$$\rho \dot{\Psi} \leq \mathbf{T} : \mathbf{D} \quad (1.1)$$

### 1.2 Motion of Fluid

The motion of the fluid is described by the function  $\mathbf{x} = \varphi(\mathbf{X}, t)$ , in which  $\mathbf{x}$  and  $\mathbf{X}$  denote reference and current position, respectively in the fluid. We assume that  $\varphi(\mathbf{X}, t)$  is smoothly invertible in its arguments, and define the deformation gradient  $\mathbf{F}$  by

$$\mathbf{F} = \nabla_{\mathbf{X}} \varphi \quad (1.2)$$

If the inverse  $\mathbf{F}^{-1}$  of  $\mathbf{F}$  exists, then

$$\mathbf{L} = \dot{\mathbf{F}} \mathbf{F}^{-1} \quad (1.3)$$

For any sufficiently smooth functions  $\mathbf{F}$  and  $\mathbf{A}$ ,

$$\dot{\Psi}(\mathbf{F}, \mathbf{A}) = \dot{\Psi}_{\mathbf{F}} : \dot{\mathbf{F}} + \dot{\Psi}_{\mathbf{A}} : \dot{\mathbf{A}} \quad (1.4)$$

Here  $\dot{\Psi}_{\mathbf{F}}$  and  $\dot{\Psi}_{\mathbf{A}}$  are the derivatives of  $\Psi$  with respect to  $\mathbf{F}$  and  $\mathbf{A}$

Substitution of (1.1), (1.2) and (1.3), into (1.4) gives

## References

- [1] Coleman BD and Noll W, The thermodynamics of elastic materials with heat conduction and viscosity. *Archive for Rational Mechanics and Analysis*, **13** (1963) 167-178.

[20]

TOTAL: [100]