



# Tutorial Letter 205/2/2017

## Special Relativity and Riemannian Geometry APM3713

Semester 2

Department of Mathematical Sciences

**IMPORTANT INFORMATION:**

This tutorial letter contains the solutions to Assignment 05.

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# Memo for Assignment 5 S2 2017

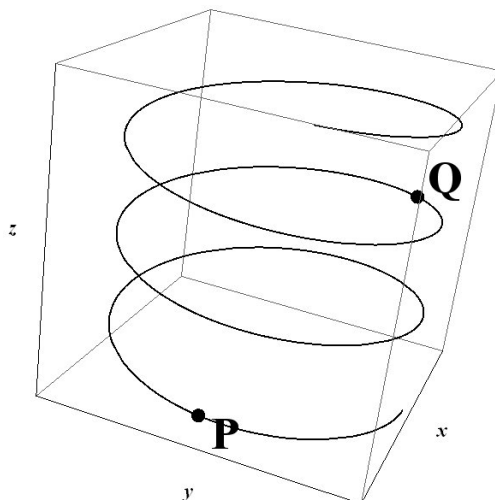
## Basics of differential geometry (§ 3)

### Question 1: Arc length

The equation for a length of a curve in an Euclidean plane can easily be generalized to give the length of a curve that exists in Euclidean (normal) three dimensional space. The length of such a space curve is given by

$$L(P, Q) = \int_P^Q dl = \int_{u_P}^{u_Q} \left( \left( \frac{dx}{du} \right)^2 + \left( \frac{dy}{du} \right)^2 + \left( \frac{dz}{du} \right)^2 \right)^{1/2} du$$

Consider the circular helix described by  $x = \sin u$ ,  $y = \cos u$  and  $z = u/10$  with the points P and Q defined by the points where  $u_P = \pi/2$  and  $u_Q = 15\pi/4$  as shown in the figure below.



What is the length of the curve between points P and Q in arbitrary units?

- 18.79
- 13.42

- 10.26\*
- 10.31
- 1.02

First we calculate the derivatives of the Cartesian coordinates with respect the the parameter  $u$ .

$$\begin{aligned}\frac{dx}{du} &= \frac{d}{du} (\sin u) = \cos u \\ \frac{dy}{du} &= \frac{d}{du} (\cos u) = -\sin u \\ \frac{dz}{du} &= \frac{d}{du} \left( \frac{u}{10} \right) = \frac{1}{10}\end{aligned}$$

The length of the helix is then given by

$$\begin{aligned}L(P, Q) &= \int_{u_P}^{u_Q} \left( \left( \frac{dx}{du} \right)^2 + \left( \frac{dy}{du} \right)^2 + \left( \frac{dz}{du} \right)^2 \right)^{1/2} du \\ &= \int_{\pi/2}^{15\pi/4} \left( \cos^2 u + \sin^2 u + \frac{1}{100} \right)^{1/2} du \\ &= \int_{\pi/2}^{15\pi/4} \left( 1 + \frac{1}{100} \right)^{1/2} du \\ &= \int_{\pi/2}^{15\pi/4} \left( \frac{101}{100} \right)^{1/2} du \\ &= \int_{\pi/2}^{15\pi/4} \frac{\sqrt{101}}{10} du \\ &= \left[ \frac{\sqrt{101}}{10} u \right]_{u=\pi/2}^{u=15\pi/4} \\ &= \frac{\sqrt{101}}{10} \left( \frac{15\pi}{4} \right) - \frac{\sqrt{101}}{10} \left( \frac{\pi}{2} \right) \\ &= \frac{13\pi\sqrt{101}}{40} \\ &= 10.26\end{aligned}$$

## Question 2: Metric tensor

The line element for a certain two dimensional Riemann space is given by

$$dl^2 = dr^2 + 2r \sin \phi dr d\phi + r^2 d\phi^2 .$$

What is the metric tensor of this space?

- $\begin{pmatrix} 1 & 2r \sin \phi \\ 2r \sin \phi & r^2 \end{pmatrix}$
- $\begin{pmatrix} 1 & r \sin \phi \\ r \sin \phi & r^2 \end{pmatrix}^*$
- $\begin{pmatrix} r \sin \phi & 1 \\ 1 & r \sin \phi \end{pmatrix}$
- $\begin{pmatrix} r^2 & 2r \sin \phi \\ 0 & 1 \end{pmatrix}$
- $\begin{pmatrix} 1 & 0 \\ 2r \sin \phi & r^2 \end{pmatrix}$

The line element for a general Riemann space is given by

$$dl^2 = \sum_{i,j=1}^n g_{ij} dx^i dx^j$$

Since we are considering a two dimensional space ( $n = 2$ ), we can expand this to

$$dl^2 = g_{11} dx^1 dx^1 + g_{12} dx^1 dx^2 + g_{21} dx^2 dx^1 + g_{22} dx^2 dx^2$$

Choosing  $x^1 = r$  and  $x^2 = \phi$ , we get

$$dl^2 = g_{11} dr^2 + g_{12} dr d\phi + g_{21} d\phi dr + g_{22} d\phi^2$$

The metric tensor must be symmetric. (This ensures that the distance from the point P to the point Q will be the same as the distance from point Q to point P.) This means that

we must have  $g_{12} = g_{21}$ . From the given line element, we can see that we have  $g_{11} = 1$ ,  $g_{12} = g_{21} = r \sin \phi$  and  $g_{22} = r^2$ . Putting this in array format gives

$$\begin{pmatrix} 1 & r \sin \phi \\ r \sin \phi & r^2 \end{pmatrix}.$$

### Question 3: Kronecker delta

The sum

$$\sum_{i=1}^3 \delta_{ii}$$

is equal to...

- 0
- 1
- 2
- **3\***
- 4

The definition of the Kronecker delta is

$$\delta_{ij} = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$$

It is a very common mistake to say that this sum is equal to 1. But it is a sum over number of components equal to 1 and the answer will depend on the number of dimensions you are working in. In this case

$$\begin{aligned} \sum_{i=1}^3 \delta_{ii} &= \delta_{11} + \delta_{22} + \delta_{33} \\ &= 1 + 1 + 1 \\ &= 3 \end{aligned}$$

### Question 4: Covariant and contravariant forms of vectors

Equation 2.70 in the textbook is written for four dimensional Minkowski space and gives a rule to determine the covariant form of a vector if the metric and contravariant form is known. This same equation written for a general two dimensional space is

$$A_j = \sum_{i=1}^2 g_{ij} A^i .$$

Use this to determine the covariant form of  $[A^i]$  in two dimensional space described by the surface of a unit sphere. The metric tensor (with  $x^1 = \theta$  and  $x^2 = \phi$ ) for this space is

$$[g_{ij}] = \begin{pmatrix} 1 & 0 \\ 0 & \sin^2 \theta \end{pmatrix}$$

and let

$$[A^i] = \begin{pmatrix} \pi \\ \pi/4 \end{pmatrix} .$$

- $[A_i] = \begin{pmatrix} \pi \\ 1/2 \end{pmatrix}$
- $[A_i] = \begin{pmatrix} \pi \\ \pi/(4\sqrt{2}) \end{pmatrix}$
- $[A_i] = \begin{pmatrix} \pi \\ \pi/2 \end{pmatrix}$
- $[A_i] = \begin{pmatrix} \pi \\ \pi/8 \end{pmatrix}^*$
- $[A_i] = \begin{pmatrix} \pi \\ \pi/4 \end{pmatrix}$

Expanding the given equation for determining the covariant components of  $[A^i]$  gives

$$\begin{aligned} A_j &= \sum_{i=1}^2 g_{ij} A^i \\ &= g_{1j} A^1 + g_{2j} A^2 \end{aligned}$$

From the information given in the question, we know that  $g_{11} = 1$ ,  $g_{12} = g_{21} = 0$ ,  $g_{22} = \sin^2 \theta$ ,  $A^1 = \pi$  and  $A^2 = \pi/4$ . The covariant components are then given by

$$\begin{aligned} A_1 &= g_{11}A^1 + g_{21}A^2 \\ &= (1)(\pi) + (0)(\pi/4) \\ &= \pi \end{aligned}$$

$$\begin{aligned} A_2 &= g_{12}A^1 + g_{22}A^2 \\ &= (0)(\pi) + (\sin^2 \theta)(\pi/4) \\ &= \frac{\pi}{4} \sin^2 \theta \end{aligned}$$

You could also have computed it with

$$\begin{aligned} [A_i] &= [g_{ij}] [A^j] \\ &= \begin{pmatrix} 1 & 0 \\ 0 & \sin^2 \theta \end{pmatrix} \begin{pmatrix} \pi \\ \pi/4 \end{pmatrix} \\ &= \begin{pmatrix} \pi \\ \frac{\pi}{4} \sin^2 \theta \end{pmatrix} \end{aligned}$$

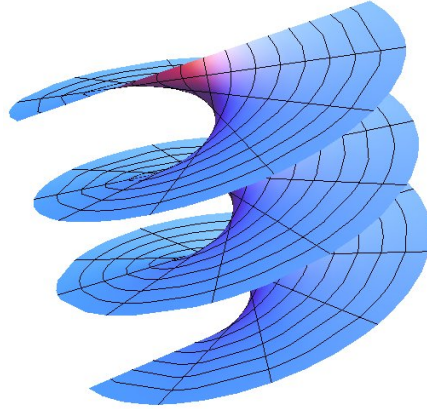
## Question 5: Riemann tensor

Calculate  $R^1_{221}$  of the right helicoid shown below that is parametrized as

$$\begin{aligned} x &= u \cos v \\ y &= u \sin v \\ z &= cv \end{aligned}$$

where  $c$  is a constant and  $x^1 = u$  and  $x^2 = v$  if it is given that the only non-zero Christoffel coefficients for the surface are

$$\begin{aligned} \Gamma^2_{12} &= \Gamma^2_{21} = \frac{u}{u^2 + c^2} \\ \Gamma^1_{22} &= \frac{-u}{u^2 + c^2} \end{aligned}$$



- $(c^2 - 2u^2)(u^2 + c^2)^{-2}$ \*
- $-c^2(u^2 + c^2)^{-2}$
- $c^2(u^2 + c^2)^{-2}$
- $-u(c^2 + u + u^2)(u^2 + c^2)^{-2}$
- $-u^2(u^2 + c^2)^{-2}$

Using equation 3.35 in the textbook, the element  $R^1_{221}$  of the Riemann tensor is given by

$$\begin{aligned} R^1_{221} &= \frac{\partial \Gamma^1_{21}}{\partial x^2} - \frac{\partial \Gamma^1_{22}}{\partial x^1} + \sum_m \Gamma^m_{21} \Gamma^1_{m2} - \sum_m \Gamma^m_{22} \Gamma^1_{m1} \\ &= \frac{\partial \Gamma^1_{21}}{\partial x^2} - \frac{\partial \Gamma^1_{22}}{\partial x^1} + (\Gamma^1_{21} \Gamma^1_{12} + \Gamma^2_{21} \Gamma^1_{22}) - (\Gamma^1_{22} \Gamma^1_{11} + \Gamma^2_{22} \Gamma^1_{21}) \end{aligned}$$

Substituting all the zero Christoffel symbols, this reduces to

$$R^1_{221} = -\frac{\partial \Gamma^1_{22}}{\partial x^1} + \Gamma^2_{21} \Gamma^1_{22}$$

Substituting the given values for the non-zero Christoffel symbols and using  $x^1 = u$  gives

$$\begin{aligned} R^1_{221} &= -\frac{\partial}{\partial u} \left( \frac{-u}{u^2 + c^2} \right) + \left( \frac{u}{u^2 + c^2} \right) \left( \frac{-u}{u^2 + c^2} \right) \\ &= \frac{c^2 - u^2}{(u^2 + c^2)^2} - \frac{u^2}{(u^2 + c^2)^2} \\ &= \frac{c^2 - 2u^2}{(u^2 + c^2)^2} \end{aligned}$$